

# ADAPTIVE STRUCTURED POOLING FOR ACTION RECOGNITION

## OBJECTIVES

### What do we want to do?

- Find coherent spatio-temporal regions in video
- Build a structured representation of a video

### How do we do it?

- Cluster HSTS [4] according to their overlap
- Define soft pooling regions from each cluster
- Link overlapping clusters in a graph structure
- Graphs comparison with GraphHopper kernel [1]

## HSTS

- Hierarchical Space-Time Segments (HSTS) represent spatio-temporal dynamic portions of a video preserving both moving and static relevant regions
- Obtained by a hierarchical segmentation relying both on image and motion and short term tracking, see [4]

## SOFT POOLING WEIGHTS

Weighted pooling map  $M_k$  by accumulating, in each frame  $t$  at each position  $p$ , segments of a HSTS set  $S_k$ :

$$M_k^t = \sum_{s \in S_k^t} \Psi_s$$

where  $s \in S_k^t$  and  $\Psi_s(p) = 1$  if  $p \in s$  and  $\Psi_s(p) = 0$  otherwise.  $M_k^t$  is L1-normalized and square-rooted. For a video of  $T$  frames:

$$M_k(x, y, t) = \{M_k^1(x, y) \dots M_k^T(x, y)\}$$

For each feature  $x_m \in X$ , with  $(x_m, y_m, t_m)$  as spatio-temporal coordinates of its centroid, weight  $w_m^k$  as a local integral of the pooling map  $M_k$ :

$$w_m^k = \int_{x_m - v_x}^{x_m + v_x} \int_{y_m - v_y}^{y_m + v_y} \int_{t_m - v_t}^{t_m + v_t} M_k(x, y, t) dx dy dt$$

## SOFT FISHER ENCODING

Given the GMM  $u_\lambda = \sum_{n=1}^N \omega_n u_n(x; \mu_n, \sigma_n)$  and the  $M$  features of  $X$ , mean  $\mathcal{G}_n^\mu(X)$  and covariance elements  $\mathcal{G}_n^\sigma(X)$  of a Fisher vector for each  $u_n$ :

$$\mathcal{G}_n^\mu(X) = \frac{1}{\sqrt{\omega_n}} \sum_{m=1}^M w_m \gamma_n(x_m) \left( \frac{x_m - \mu_n}{\sigma_n} \right),$$

$$\mathcal{G}_n^\sigma(X) = \frac{1}{\sqrt{2\omega_n}} \sum_{m=1}^M w_m \gamma_n(x_m) \left( \frac{(x_m - \mu_n)^2}{\sigma_n^2} - 1 \right),$$

where  $\gamma_n(x_m)$  is the posterior probability of the feature  $x_m$  for the component  $n$  of the GMM.

## ST STRUCTURED POOLING

The affinity  $A(s_i, s_j)$  of two segments  $s_i$  (alive from  $t_{is}$  to  $t_{ie}$ ) and  $s_j$  (alive from  $t_{js}$  to  $t_{je}$ ) is:

$$A(s_i, s_j) = \frac{1}{\min_l} \sum_{t \in [\max_s, \min_e]} \frac{s_i^t \cap s_j^t}{s_i^t \cup s_j^t}$$

where  $\min_l = \min(t_{ie} - t_{is}, t_{je} - t_{js})$ ,  $\max_s = \max(t_{is}, t_{js})$  and  $\min_e = \min(t_{ie}, t_{je})$ .

- Multiple runs of normalized cut on affinity matrix  $A$  to obtain different number of segments clusters
- Each cluster is a node in the graph, soft pooling of dense trajectories features as attribute
- Link between clusters having overlapping segments

## ADAPTIVE SPATIO-TEMPORAL STRUCTURED REPRESENTATION OF VIDEO



Weighted trajectories for exemplar active nodes on a subset of frames for action “kiss” and “handshake”.

## RESULTS

| UCF Sports             |      |           | HighFive                   |      |
|------------------------|------|-----------|----------------------------|------|
| Method                 | LOO  | Split [3] | Method                     | mAP  |
| Our (all features)     | 90.4 | 90.8      | Our (all features)         | 65.4 |
| Our (MBH only)         | 88.3 | 90.0      | Our (MBH only)             | 62.8 |
| FVB (all features)     | 88.6 | 89.4      | FVB (all features)         | 61.3 |
| Lan <i>et al.</i>      | 83.7 | 73.1      | Gaidon <i>et al.</i> [2]   | 62.4 |
| Kovashka <i>et al.</i> | 87.3 | -         | Ma <i>et al.</i> [4]       | 53.3 |
| Klaser <i>et al.</i>   | 86.7 | -         | Wang <i>et al.</i>         | 53.4 |
| Wang <i>et al.</i>     | -    | 85.2      | Laptev <i>et al.</i>       | 36.9 |
| Ma <i>et al.</i> [4]   | -    | 81.7      | Patron-Perez <i>et al.</i> | 42.4 |

## CONCLUSIONS

- Structured representation adaptive to video content that does not rely on fixed partition of space or time
- Unsupervised procedure to generate a structured representation of the video
- Jointly models the hierarchical and spatio-temporal relationship without imposing a strict hierarchy
- Significant improvement over the state-of-the-art on two standard datasets

## REFERENCES

- [1] Aasa Feragen, Niklas Kasenburg, Jens Petersen, Marleen de Bruijne, and Karsten Borgwardt. Scalable kernels for graphs with continuous attributes. In *Advances in Neural Information Processing Systems*, pages 216–224, 2013.
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- [3] Tian Lan, Yang Wang, and Greg Mori. Discriminative figure-centric models for joint action localization and recognition. In *Proc. of International Conference on Computer Vision (ICCV)*, pages 2003–2010. IEEE, 2011.
- [4] Shugao Ma, Jianming Zhang, Nazli Ikizler-Cinbis, and Stan Sclaroff. Action recognition and localization by hierarchical space-time segments. In *Proc. of International Conference on Computer Vision (ICCV)*. IEEE, 2013.